

Introduction

Personalization in learning and delivery mechanisms can advance sensorimotor training outcomes across domains and user types. In this work we introduce a framework to support and evaluate personalization within virtual reality (VR) based systems.

- Rationale:** Human sensorimotor learning has several dimensions, and VR enables an embodied training interface to promote useful behaviors.
- Hypothesis:** Personalization driven by performance, neurophysiological, and behavioral (PNB) data can accelerate learning. This personalization can be proficiency- or deficiency-driven, with adaptation at baseline or downstream resulting in better outcomes.
- Approach:** This work is mostly prospective, where we present evidence of using baseline PNB data for predicting performance behaviors in one VR context and discuss how that could carry forward towards a generalizable framework for adaptation.

A framework for personalization

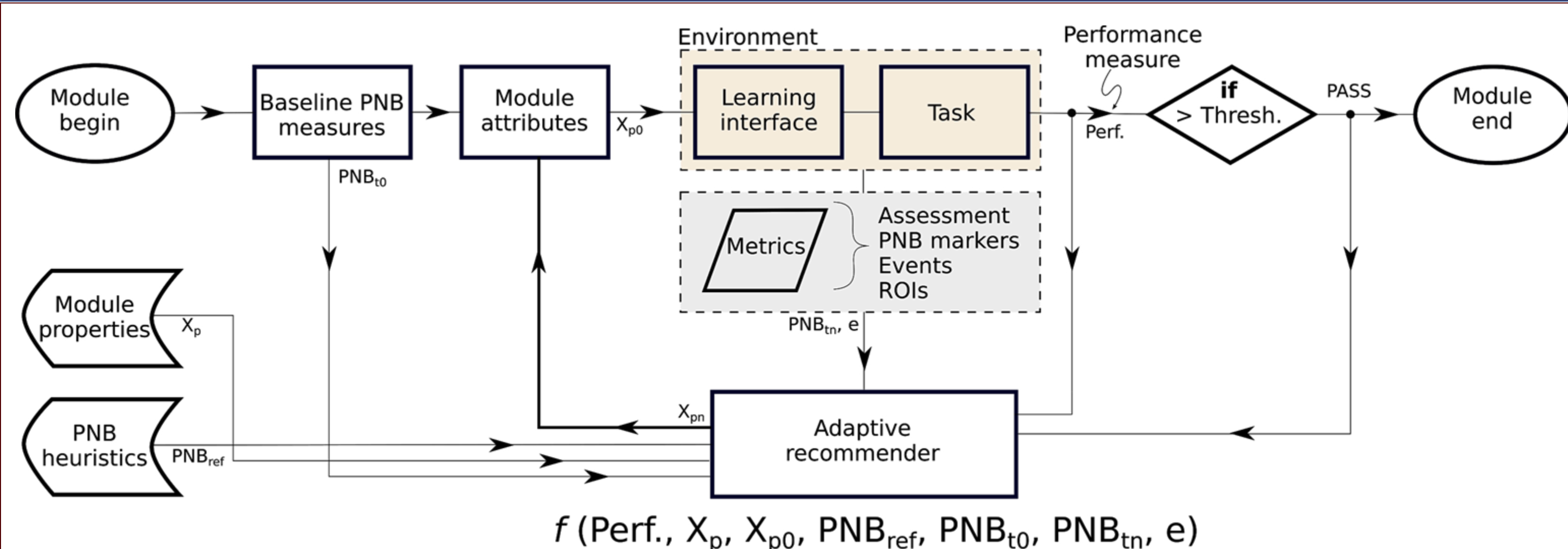


Fig. 1: Schematic representation of a technology-agnostic framework for personalization, and adaptability across learning environments and objectives.

Personalization for human learning can build on three key elements:

- Actionable metrics** that determine need for personalization
- Adaptable elements** within a learning environment or interface
- A **guiding strategy** to facilitate personalization or adaptations

VR training on firefighters

Forty participants were recruited from the Bryan-College Station Fire Department, who were cast into stress learning and control learning groups within a single-blind experiment protocol.

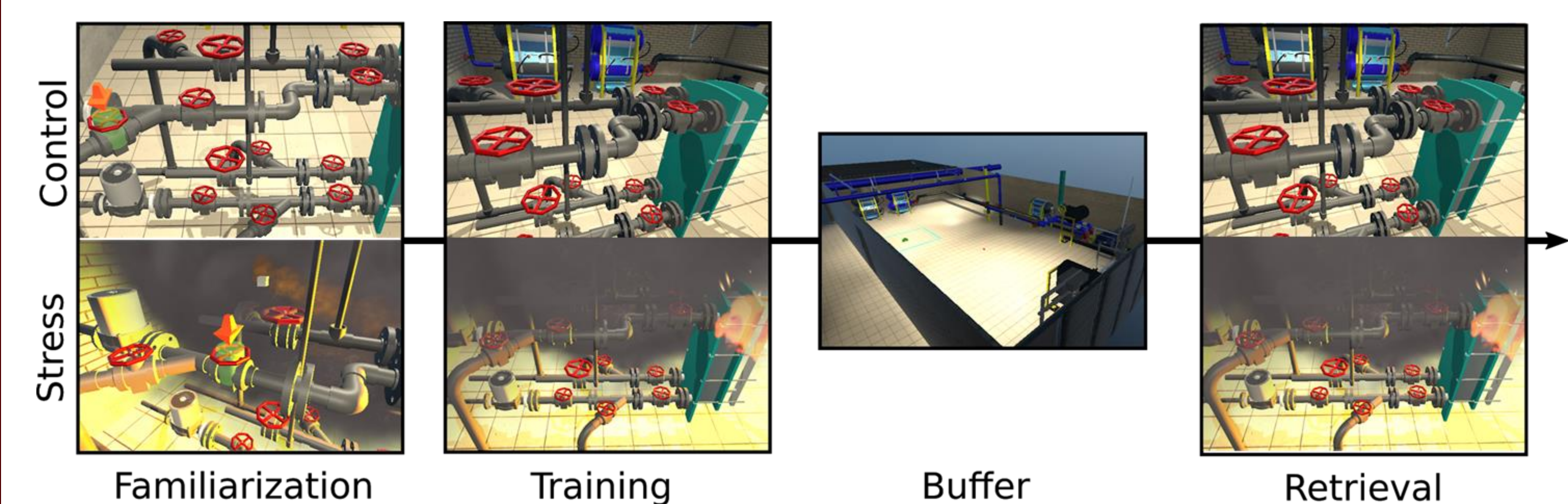


Fig. 2: (a) The experiment workflow during the VR valve sequence execution task. (b) Snapshot of an instrumented participant (RIGHT).

The task entailed distinct encoding, retention and recall phases, with audiovisual perturbations.

- Performance:** Correctness, time
- Neurophysiological:** fNIRS, ECG, EDA, eye and head movement
- Behavioral:** Subjective questionnaires between trials, and between levels subjective responses



Baseline measures as performance indicators

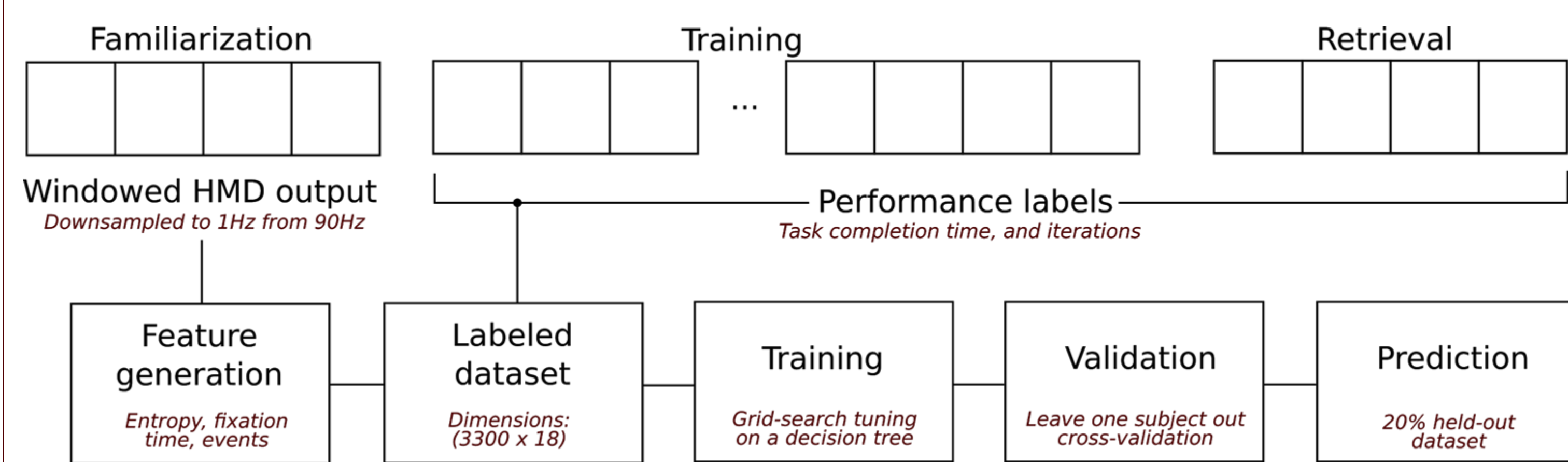


Fig. 4: The machine learning workflow used takes a supervised approach where observations are labeled based on a composite performance score that includes completion time, and response correctness.

GROUP	ACCURACY (%)	PRECISION	RECALL
CONTROL	86.21	78.24	71.18
STRESS	67.74	62.14	58.14
OVERALL	71.04	71.16	64.13

Table 1: User stratification based on baseline gaze data. All measures indicate mean values from the cross-validated output.

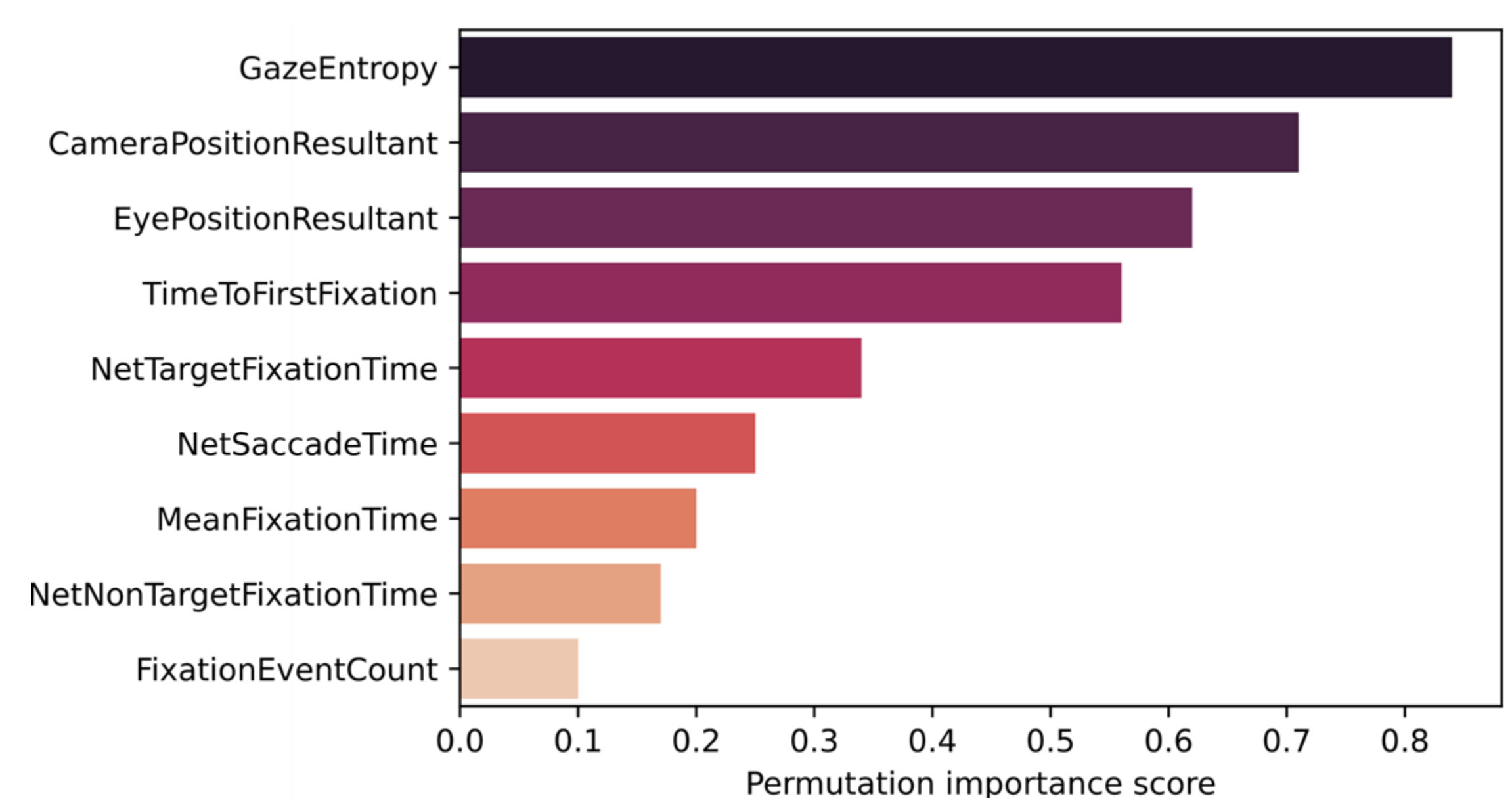
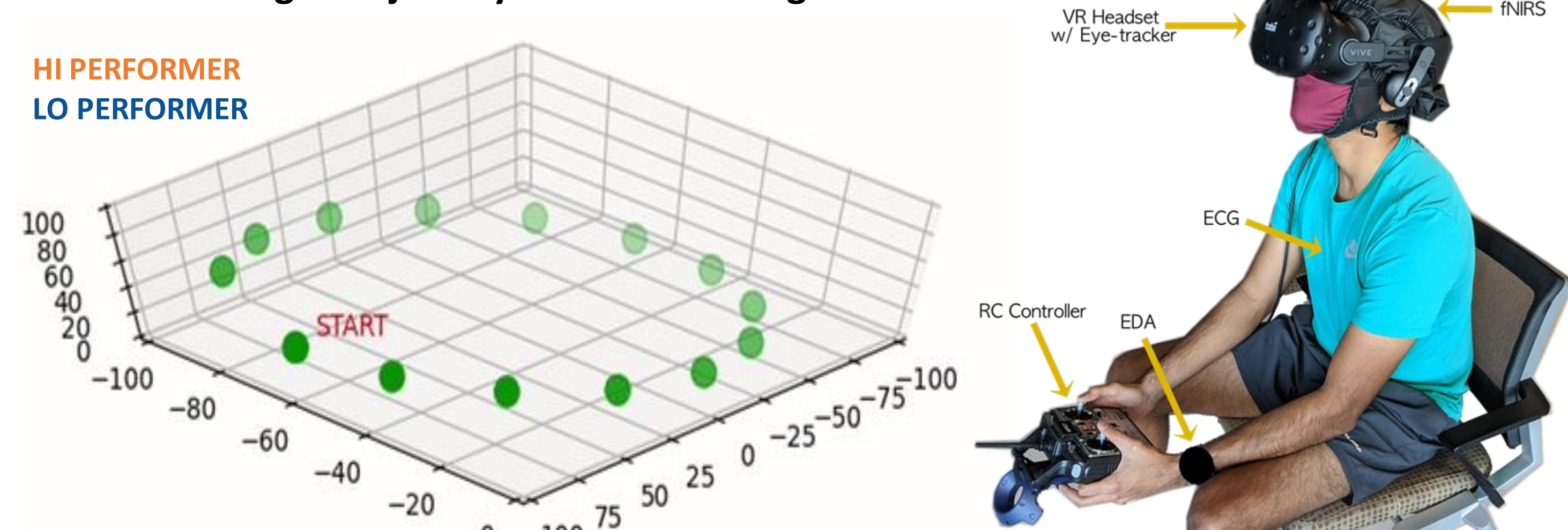


Fig. 4: Permutation importance scores for the top nine model variables used by the cross-validated model. Gaze entropy and camera position-based features were identified as key components for performance stratification.

Towards generalizability

Drone flight trajectory with event recognition



LO1: Familiarization	LO2: Navigation	LO3: Precision	LO4: Maneuvering	LO5: Resilience
----------------------	-----------------	----------------	------------------	-----------------

Fig. 5: Drone flight training in VR using a real-world RC controller. (a) Trajectory differences between high, and low performers. (b) Instrumented participant (RIGHT). (c) Training stages with learning objectives (LO).

- This framework is now being explored across technology and task domains on an NSF convergence accelerator-driven project.
- Brain-metrics in an offline sense can enable state-driven personalization.
- Further explorations underway to determine the efficacy of *macro* or *micro*-adaptations.